

A Detailed Guide to `spmodel`

Michael Dumelle, Matt Higham, and Jay M. Ver Hoef

1 Introduction

`spmodel` is an **R** package used to fit, summarize, and predict for a variety of spatial statistical models. The vignette provides an introduction to both the basic and advanced features of the `spmodel` package coupled with a brief theoretical explanation of the methods. In Section 2, we give a brief theoretical introduction to spatial linear models. In Section 3, we outline the variety of methods used to estimate the parameters of spatial linear models. In Section 4, we explain how to obtain predictions at unobserved locations. In Section 5, we detail some advanced modeling features, including random effects, partition factors, anisotropy, big data approaches, and spatial generalized linear models. In Section 6, we end with a short discussion. Before proceeding, we load `spmodel` by running

```
library(spmodel)
```

If using `spmodel` in a formal publication or report, please cite it. Citing `spmodel` lets us devote more resources to the package in the future. We view the `spmodel` citation by running

```
citation(package = "spmodel")
```

```
#>
#> To cite spmodel in publications use:
#>
#>   Dumelle M, Higham M, Ver Hoef JM (2023). spmodel: Spatial statistical
#>   modeling and prediction in R. PLOS ONE 18(3): e0282524.
#>   https://doi.org/10.1371/journal.pone.0282524
#>
#> A BibTeX entry for LaTeX users is
#>
#>   @Article{,
#>     title = {{spmodel}: Spatial statistical modeling and prediction in {R}},
#>     author = {Michael Dumelle and Matt Higham and Jay M. {Ver Hoef}},
#>     journal = {PLOS ONE},
#>     year = {2023},
#>     volume = {18},
#>     number = {3},
#>     pages = {1--32},
#>     doi = {10.1371/journal.pone.0282524},
#>     url = {https://doi.org/10.1371/journal.pone.0282524},
#>   }
```

There are two additional vignettes in `spmodel`. The first provides an overview of basic features in `spmodel` and can be viewed by running `vignette("basics", "spmodel")`. The second provides technical details regarding many of the functions in `spmodel` and can be viewed by running `vignette("technical", "spmodel")`.

We will create visualizations using `ggplot2` (Wickham 2016), which we load by running

```
library(ggplot2)
```

ggplot2 is only installed alongside `spmodel` when `dependencies = TRUE` in `install.packages()`, so check that the package is installed and loaded before reproducing any of these vignette’s visualizations. We will also show code that can be used to create interactive visualizations of spatial data with `mapview` (Appelhans et al. 2022). `mapview` also has many backgrounds available that contextualize spatial data with topographical information. Before running the `mapview` code interactively, make sure `mapview` is installed and loaded.

`spmodel` contains various methods for generic functions defined outside of `spmodel`. To find relevant documentation for these methods, run `help("generic.spmodel", "spmodel")` (e.g., `help("summary.spmodel", "spmodel")`, `help("predict.spmodel", "spmodel")`, etc.). Note that `?generic.spmodel` is shorthand for `help("generic.spmodel", "spmodel")`. We provide more details and examples regarding these methods and generics throughout this vignette. For a full list of `spmodel` functions available, see `spmodel`’s documentation manual.

2 The Spatial Linear Model

Statistical linear models are often parameterized as

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}, \quad (1)$$

where for a sample size n , \mathbf{y} is an $n \times 1$ column vector of response variables, \mathbf{X} is an $n \times p$ design (model) matrix of explanatory variables, $\boldsymbol{\beta}$ is a $p \times 1$ column vector of fixed effects controlling the impact of \mathbf{X} on \mathbf{y} , and $\boldsymbol{\epsilon}$ is an $n \times 1$ column vector of random errors. We typically assume that $E(\boldsymbol{\epsilon}) = \mathbf{0}$ and $\text{Cov}(\boldsymbol{\epsilon}) = \sigma_{\epsilon}^2 \mathbf{I}$, where $E(\cdot)$ denotes expectation, $\text{Cov}(\cdot)$ denotes covariance, σ_{ϵ}^2 denotes a variance parameter, and \mathbf{I} denotes the identity matrix.

The model in Equation 1 assumes the elements of \mathbf{y} are uncorrelated. Typically for spatial data, elements of \mathbf{y} are correlated, as observations close together in space tend to be more similar than observations far apart (Tobler 1970). Failing to properly accommodate the spatial dependence in \mathbf{y} can cause researchers to draw incorrect conclusions about their data. To accommodate spatial dependence in \mathbf{y} , an $n \times 1$ spatial random effect, $\boldsymbol{\tau}$, is added to Equation 1, yielding the model

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\tau} + \boldsymbol{\epsilon}, \quad (2)$$

where $\boldsymbol{\tau}$ is independent of $\boldsymbol{\epsilon}$, $E(\boldsymbol{\tau}) = \mathbf{0}$, $\text{Cov}(\boldsymbol{\tau}) = \sigma_{\tau}^2 \mathbf{R}$, \mathbf{R} is a matrix that determines the spatial dependence structure in \mathbf{y} and depends on a range parameter, ϕ . We discuss \mathbf{R} in more detail shortly. The parameter σ_{τ}^2 is called the spatially dependent random error variance or partial sill. The parameter σ_{ϵ}^2 is called the spatially independent random error variance or nugget. These two variance parameters are henceforth more intuitively written as σ_{de}^2 and σ_{ie}^2 , respectively. The covariance of \mathbf{y} is denoted $\boldsymbol{\Sigma}$ and given by $\sigma_{de}^2 \mathbf{R} + \sigma_{ie}^2 \mathbf{I}$. The parameters that compose this covariance are contained in the vector $\boldsymbol{\theta}$, which is called the covariance parameter vector.

Equation 2 is called the spatial linear model. The spatial linear model applies to both point-referenced and areal (i.e., lattice) data. Spatial data are point-referenced when the elements in \mathbf{y} are observed at point-locations indexed by x-coordinates and y-coordinates on a spatially continuous surface with an infinite number of locations. The `splm()` function is used to fit spatial linear models for point-referenced data (these are sometimes called geostatistical models). One spatial covariance function available in `splm()` is the exponential spatial covariance function, which has an \mathbf{R} matrix given by

$$\mathbf{R} = \exp(-\mathbf{M}/\phi),$$

where \mathbf{M} is a matrix of Euclidean distances among observations. Recall that ϕ is the range parameter, controlling the behavior of the covariance function as a function of distance. Parameterizations for `splm()` spatial covariance types and their \mathbf{R} matrices can be seen by running `help("splm", "spmodel")` or

`vignette("technical", "spmodel")`. Some of these spatial covariance types (e.g., Matérn) depend on an extra parameter beyond σ_{de}^2 , σ_{ie}^2 , and ϕ .

Spatial data are areal when the elements in \mathbf{y} are observed as part of a finite network of polygons whose connections are indexed by a neighborhood structure. For example, the polygons may represent counties in a state that are neighbors if they share at least one boundary. Areal data are often equivalently called lattice data (Cressie 1993). The `spautorm()` function is used to fit spatial linear models for areal data (these are sometimes called spatial autoregressive models). One spatial autoregressive covariance function available in `spautorm()` is the simultaneous autoregressive spatial covariance function, which has an \mathbf{R} matrix given by

$$\mathbf{R} = [(\mathbf{I} - \phi\mathbf{W})(\mathbf{I} - \phi\mathbf{W})^\top]^{-1},$$

where \mathbf{W} is a weight matrix describing the neighborhood structure in \mathbf{y} . Parameterizations for `spautorm()` spatial covariance types and their \mathbf{R} matrices can be seen by running `help("spautorm", "spmodel")` or `vignette("technical", "spmodel")`.

One way to define \mathbf{W} is through queen contiguity (Anselin, Syabri, and Kho 2010). Two observations are queen contiguous if they share a boundary. The ij th element of \mathbf{W} is then one if observation i and observation j are queen contiguous and zero otherwise. Observations are not considered neighbors with themselves, so each diagonal element of \mathbf{W} is zero.

Sometimes each element in the weight matrix \mathbf{W} is divided by its respective row sum. This is called row-standardization. Row-standardizing \mathbf{W} has several benefits, which are discussed in detail by Ver Hoef et al. (2018).

3 Model Fitting

In this section, we show how to use the `splm()` and `spautorm()` functions to estimate parameters of the spatial linear model. We also explore diagnostic tools in `spmodel` that evaluate model fit. The `splm()` and `spautorm()` functions share similar syntactic structure with the `lm()` function used to fit linear models without spatial dependence from Equation 1. `splm()` and `spautorm()` generally require at least three arguments:

- **formula**: a formula that describes the relationship between the response variable (\mathbf{y}) and explanatory variables (\mathbf{X})
 - formula in `splm()` is the same as formula in `lm()`
- **data**: a `data.frame` or `sf` object that contains the response variable, explanatory variables, and spatial information
- **spcov_type**: the spatial covariance type ("exponential", "matern", "car", etc)

If `data` is an `sf` (Pebesma 2018) object, spatial information is stored in the object's geometry. If `data` is a `data.frame`, then the x-coordinates and y-coordinates must be provided via the `xcoord` and `ycoord` arguments (for point-referenced data) or the weight matrix must be provided via the `W` argument (for areal data). Appendix A uses the `caribou` data, a `tibble` (a special `data.frame`), to show how to provide spatial information via `xcoord` and `ycoord` (in `splm()`) or `W` (in `spautorm()`).

In the following subsections, we use the point-referenced `moss` data, an `sf` object that contains data on heavy metals in mosses near a mining road in Alaska. We view the first few rows of `moss` by running

```
moss

#> Simple feature collection with 365 features and 7 fields
#> Geometry type: POINT
#> Dimension:      XY
#> Bounding box:   xmin: -445884.1 ymin: 1929616 xmax: -383656.8 ymax: 2061414
#> Projected CRS: NAD83 / Alaska Albers
#> # A tibble: 365 x 8
#>   sample field_dup lab_rep year  sideroad log_dist2road log_Zn
#>   <fct>  <fct>      <fct>  <fct> <fct>      <dbl>  <dbl>
```

```
#> 1 001PR 1 1 2001 N 2.68 7.33
#> 2 001PR 1 2 2001 N 2.68 7.38
#> 3 002PR 1 1 2001 N 2.54 7.58
#> 4 003PR 1 1 2001 N 2.97 7.63
#> 5 004PR 1 1 2001 N 2.72 7.26
#> 6 005PR 1 1 2001 N 2.76 7.65
#> 7 006PR 1 1 2001 S 2.30 7.59
#> 8 007PR 1 1 2001 N 2.78 7.16
#> 9 008PR 1 1 2001 N 2.93 7.19
#> 10 009PR 1 1 2001 N 2.79 8.07
#> # ... with 355 more rows, and 1 more variable: geometry <POINT [m]>
```

We can learn more about `moss` by running `help("moss", "spmodel")`, and we can visualize the distribution of log zinc concentration in `moss` (Figure 1) by running

```
ggplot(moss, aes(color = log_Zn)) +
  geom_sf() +
  scale_color_viridis_c() +
  theme_gray(base_size = 14)
```

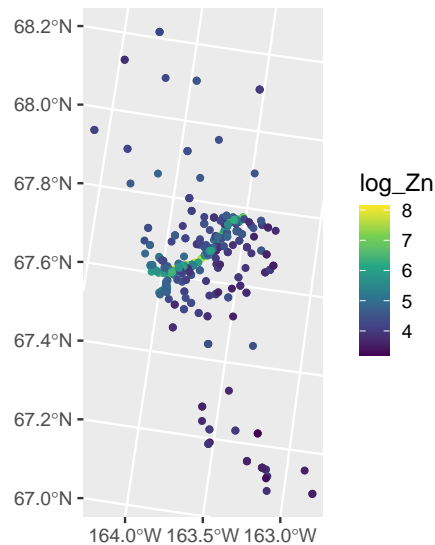


Figure 1: Distribution of log zinc concentration in the moss data.

Log zinc concentration can be viewed interactively in `mapview` by running

```
mapview(moss, zcol = "log_Zn")
```

3.1 Estimation

Generally the covariance parameters (θ) and fixed effects (β) of the spatial linear model require estimation. The default estimation method in `spmodel` is restricted maximum likelihood (Patterson and Thompson 1971; Harville 1977; Wolfinger, Tobias, and Sall 1994), but the estimation method can be changed with the `estmethod` argument to `splm()` or `spautocor()`. Maximum likelihood estimation is also available. For point-referenced data, semivariogram weighted least squares (Cressie 1985) and semivariogram composite likelihood (Curriero and Lele 1999) are additional estimation methods. The estimation method is chosen using the `estmethod` argument.

We estimate parameters of a spatial linear model regressing log zinc concentration (`log_Zn`) on log distance

to a haul road (`log_dist2road`) using an exponential spatial covariance function by running

```
spmod <- splm(log_Zn ~ log_dist2road, moss, spcov_type = "exponential")
```

We summarize the model fit by running

```
summary(spmod)
```

```
#>
#> Call:
#> splm(formula = log_Zn ~ log_dist2road, data = moss, spcov_type = "exponential")
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -2.6801 -1.3606 -0.8103 -0.2485  1.1298
#>
#> Coefficients (fixed):
#>              Estimate Std. Error z value Pr(>|z|)
#> (Intercept)   9.76825    0.25216   38.74  <2e-16 ***
#> log_dist2road -0.56287    0.02013  -27.96  <2e-16 ***
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Pseudo R-squared:  0.683
#>
#> Coefficients (exponential spatial covariance):
#>      de      ie    range
#> 3.595e-01 7.897e-02 8.237e+03
```

The fixed effects coefficient table contains estimates, standard errors, z-statistics, and asymptotic p-values for each fixed effect. From this table, we notice there is evidence that mean log zinc concentration significantly decreases with distance from the haul road (p-value < 2e-16). We see the fixed effect estimates by running

```
coef(spmod)
```

```
#> (Intercept) log_dist2road
#>  9.7682525  -0.5628713
```

The model summary also contains the exponential spatial covariance parameter estimates, which we can view by running

```
coef(spmod, type = "spcov")
```

```
#>      de      ie    range    rotate    scale
#> 3.595316e-01 7.896824e-02 8.236712e+03 0.000000e+00 1.000000e+00
#> attr("class")
#> [1] "exponential"
```

The dependent random error variance (σ_{de}^2) is estimated to be approximately 0.36 and the independent random error variance (σ_{ie}^2) is estimated to be approximately 0.079. The range (ϕ) is estimated to be approximately 8,237. The effective range is the distance at which the spatial covariance is approximately zero. For the exponential covariance, the effective range is 3ϕ . This means that observations whose distance is greater than 24,711 meters are approximately uncorrelated. The `rotate` and `scale` parameters affect the modeling of anisotropy (Section 5.5). By default, they are assumed to be zero and one, respectively, which means that anisotropy is not modeled (i.e., the spatial covariance is assumed isotropic, or independent of direction). We plot the fitted spatial covariance function (Figure 2) by running

```
plot(spmod, which = 7)
```

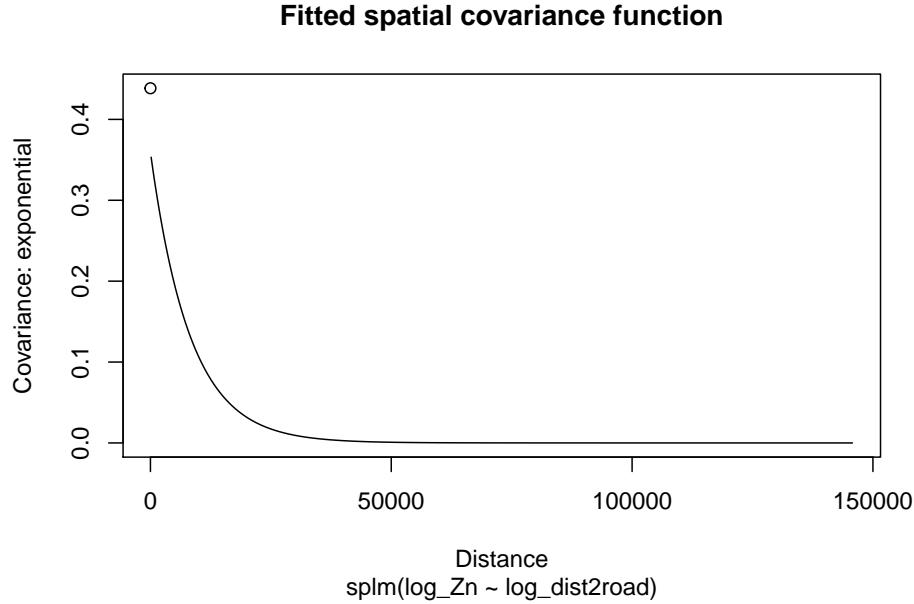


Figure 2: Empirical spatial covariance of fitted model.

We can learn more about the plots available for fitted models by running `help("plot.splm", "spmodel")`.

3.2 Model-Fit Statistics

The quality of model fit can be assessed using a variety of statistics readily available in `spmodel`. The first model-fit statistic we consider is the pseudo R-squared. The pseudo R-squared is a generalization of the classical R-squared from non-spatial linear models that quantifies the proportion of variability in the data explained by the fixed effects. The pseudo R-squared is defined as

$$PR2 = 1 - \frac{\mathcal{D}(\hat{\Theta})}{\mathcal{D}(\hat{\Theta}_0)},$$

where $\mathcal{D}(\hat{\Theta})$ is the deviance of the fitted model indexed by parameter vector $\hat{\Theta}$ and $\mathcal{D}(\hat{\Theta}_0)$ is the deviance of an intercept-only model indexed by parameter vector $\hat{\Theta}_0$. For maximum likelihood, $\hat{\Theta} = \{\hat{\theta}, \hat{\beta}\}$. For restricted maximum likelihood $\hat{\Theta} = \{\hat{\theta}\}$.

We compute the pseudo R-squared by running

```
pseudoR2(spmod)
```

```
#> [1] 0.6829687
```

Roughly 68% of the variability in log zinc is explained by log distance from the road. The pseudo R-squared can be adjusted to account for the number of explanatory variables using the `adjust` argument. Pseudo R-squared (and the adjusted version) is most helpful for comparing models that have the same covariance structure.

The next two model-fit statistics we consider are the AIC and AICc. The AIC and AICc evaluate the fit of a model with a penalty for the number of parameters estimated. This penalty balances model fit and model parsimony. Lower AIC and AICc indicate a better balance of model fit and parsimony. The AICc is a correction to AIC for small sample sizes. As the sample size increases, AIC and AICc converge.

The spatial AIC and AICc are given by

$$\begin{aligned} \text{AIC} &= -2\ell(\hat{\Theta}) + 2(|\hat{\Theta}|) \\ \text{AICc} &= -2\ell(\hat{\Theta}) + 2n(|\hat{\Theta}|)/(n - |\hat{\Theta}| - 1), \end{aligned}$$

where $\ell(\hat{\Theta})$ is the log-likelihood of the data evaluated at the estimated parameter vector $\hat{\Theta}$ that maximized $\ell(\Theta)$, $|\hat{\Theta}|$ is the dimension of $\hat{\Theta}$, and n is the sample size. As with the deviance, for maximum likelihood, $\hat{\Theta} = \{\hat{\theta}, \hat{\beta}\}$, and for restricted maximum likelihood $\hat{\Theta} = \{\hat{\theta}\}$. There are some nuances to consider when comparing AIC across models: AIC comparisons between a model fit using restricted maximum likelihood and a model fit using maximum likelihood are meaningless, as the models are fit with different likelihoods; AIC comparisons between models fit using restricted maximum likelihood are only valid when the models have the same fixed effect structure; AIC comparisons between models fit using maximum likelihood are valid even when the models have different fixed effect structures (Pinheiro and Bates 2006).

Suppose we want to quantify the difference in model quality between the spatial model and a non-spatial model using the AIC and AICc criteria. We fit a non-spatial model (Equation 1) in `spmodel` by running

```
lmod <- splm(log_Zn ~ log_dist2road, moss, spcov_type = "none")
```

This model is equivalent to one fit using `lm()`. We compute the spatial AIC and AICc of the spatial model and non-spatial model by running

```
AIC(spmod, lmod)
```

```
#>      df      AIC
#> spmod  3 373.2089
#> lmod   1 636.0635
```

```
AICc(spmod, lmod)
```

```
#>      df      AICc
#> spmod  3 373.2754
#> lmod   1 636.0745
```

The noticeably lower AIC and AICc of the spatial model indicate that it is a better fit to the data than the non-spatial model. Recall that these AIC and AICc comparisons are valid because both models are fit using restricted maximum likelihood (the default).

Another approach to comparing the fitted models is to perform leave-one-out cross validation (Hastie et al. 2009). In leave-one-out cross validation, a single observation is removed from the data, the model is re-fit, and a prediction is made for the held-out observation. Then, a loss metric like mean-squared-prediction error is computed and used to evaluate model fit. The lower the mean-squared-prediction error, the better the model fit. For computational efficiency, leave-one-out cross validation in `spmodel` is performed by first estimating θ using all the data and then re-estimating only β as we predict each removed observation. We perform leave-one-out cross validation for the spatial and non-spatial model by running

```
loocv(spmod)
```

```
#> [1] 0.1110895
```

```
loocv(lmod)
```

```
#> [1] 0.3237897
```

The noticeably lower mean-squared-prediction error of the spatial model indicates that it is a better fit to the data than the non-spatial model.

3.3 Diagnostics

In addition to model fit metrics, `spmodel` provides functions that compute diagnostic metrics that help assess model assumptions and identify unusual observations.

An observation is said to have high leverage if its combination of explanatory variable values is far from the mean vector of the explanatory variables. For a non-spatial model, the leverage of the i th observation is the i th diagonal element of the hat matrix given by

$$\mathbf{H} = \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top.$$

For a spatial model, the leverage of the i th observation is the i th diagonal element of the spatial hat matrix given by

$$\mathbf{H}^* = (\mathbf{X}^*(\mathbf{X}^{*\top} \mathbf{X})^{-1} \mathbf{X}^{*\top}),$$

where $\mathbf{X}^* = \mathbf{\Sigma}^{-1/2} \mathbf{X}$ and $\mathbf{\Sigma}^{-1/2}$ is the inverse square root of the covariance matrix, $\mathbf{\Sigma}$ (Montgomery, Peck, and Vining 2021). The spatial hat matrix can be viewed as the non-spatial hat matrix applied to \mathbf{X}^* instead of \mathbf{X} . We compute the hat values (leverage) by running

```
hatvalues(spmod)
```

Larger hat values indicate more leverage, and observations with large hat values may be unusual and warrant further investigation.

The fitted value of an observation is the estimated mean response given the observation's explanatory variable values and the model fit:

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}}.$$

We compute the fitted values by running

```
fitted(spmod)
```

Fitted values for the spatially dependent random errors ($\boldsymbol{\tau}$), spatially independent random errors ($\boldsymbol{\epsilon}$), and random effects can also be obtained via `fitted()` by changing the `type` argument.

The residuals measure each response's deviation from its fitted value. The response residuals are given by

$$\mathbf{e}_r = \mathbf{y} - \hat{\mathbf{y}}.$$

We compute the response residuals of the spatial model by running

```
residuals(spmod)
```

The response residuals are typically not directly checked for linear model assumptions, as they have covariance closely resembling the covariance of \mathbf{y} . Pre-multiplying the residuals by $\mathbf{\Sigma}^{-1/2}$ yields the Pearson residuals (Myers et al. 2012):

$$\mathbf{e}_p = \mathbf{\Sigma}^{-1/2} \mathbf{e}_r.$$

When the model is correct, the Pearson residuals have mean zero, variance approximately one, and are uncorrelated. We compute the Pearson residuals of the spatial model by running

```
residuals(spmod, type = "pearson")
```

The covariance of \mathbf{e}_p is $(\mathbf{I} - \mathbf{H}^*)$, which is approximately \mathbf{I} for large sample sizes. Explicitly dividing \mathbf{e}_p by the respective diagonal element of $(\mathbf{I} - \mathbf{H}^*)$ yields the standardized residuals (Myers et al. 2012):

$$\mathbf{e}_s = \mathbf{e}_p \odot \frac{1}{\sqrt{(1 - \text{diag}(\mathbf{H}^*))}},$$

where $\text{diag}(\mathbf{H}^*)$ denotes the diagonal of \mathbf{H}^* and \odot denotes the Hadamard (element-wise) product. We compute the standardized residuals of the spatial model by running


```
residuals(spmo, type = "standardized")
```

or

```
rstandard(spmo)
```

When the model is correct, the standardized residuals have mean zero, variance one, and are uncorrelated. It is common to check linear model assumptions through visualizations. We can plot the standardized residuals vs fitted values by running

```
plot(spmo, which = 1) # figure omitted
```

When the model is correct, the standardized residuals should be evenly spread around zero with no discernible pattern. We can plot a normal QQ-plot of the standardized residuals by running

```
plot(spmo, which = 2) # figure omitted
```

When the standardized residuals are normally distributed, they should closely follow the normal QQ-line.

An observation is said to be influential if its omission has a large impact on model fit. Typically, this is measured using Cook's distance (Cook and Weisberg 1982). For the non-spatial model, the Cook's distance of the i th observation is denoted \mathbf{D} and given by

$$\mathbf{D} = \frac{\mathbf{e}_s^2}{p} \odot \text{diag}(\mathbf{H}) \odot \frac{1}{(1 - \text{diag}(\mathbf{H}))},$$

where p is the dimension of β (the number of fixed effects).

For a spatial model, the Cook's distance of the i th observation is denoted \mathbf{D}^* and given by

$$\mathbf{D}^* = \frac{\mathbf{e}_s^2}{p} \odot \text{diag}(\mathbf{H}^*) \odot \frac{1}{(1 - \text{diag}(\mathbf{H}^*))}.$$

A larger Cook's distance indicates more influence, and observations with large Cook's distance values may be unusual and warrant further investigation. We compute Cook's distance by running

```
cooks.distance(spmo)
```

The Cook's distance versus leverage (hat values) can be visualized by running

```
plot(spmo, which = 6) # figure omitted
```

Though we described the model diagnostics in this subsection using Σ , generally the covariance parameters are estimated and Σ is replaced with $\hat{\Sigma}$.

3.4 The broom functions: tidy(), glance(), and augment()

The tidy(), glance(), and augment() functions from the broom R package (Robinson, Hayes, and Couch 2021) provide convenient output for many of the model fit and diagnostic metrics discussed in the previous two sections. The tidy() function returns a tidy tibble of the coefficient table from summary():

```
tidy(spmo)
```

```
#> # A tibble: 2 x 5
#>   term          estimate std.error statistic p.value
#>   <chr>          <dbl>    <dbl>    <dbl>    <dbl>
#> 1 (Intercept)    9.77      0.252     38.7      0
#> 2 log_dist2road -0.563    0.0201   -28.0      0
```

This tibble format makes it easy to pull out the coefficient names, estimates, standard errors, z-statistics, and p-values from the summary() output.

The `glance()` function returns a tidy tibble of model-fit statistics:

```
glance(spmod)
```

```
#> # A tibble: 1 x 9
#>       n      p  npair value   AIC   AICc logLik deviance pseudo.r.squared
#>   <int> <dbl> <int> <dbl> <dbl> <dbl> <dbl>   <dbl>         <dbl>
#> 1   365     2     3   367.  373.  373.  -184.    363.           0.683
```

The `glances()` function is an extension of `glance()` that can be used to look at many models simultaneously:

```
glances(spmod, lmod)
```

```
#> # A tibble: 2 x 10
#>   model      n      p  npair value   AIC   AICc logLik deviance pseudo.r.squared
#>   <chr> <int> <dbl> <int> <dbl> <dbl> <dbl> <dbl>   <dbl>         <dbl>
#> 1 spmod   365     2     3   367.  373.  373.  -184.    363.           0.683
#> 2 lmod    365     2     1   634.  636.  636.  -317.    363.           0.671
```

Finally, the `augment()` function augments the original data with model diagnostics:

```
augment(spmod)
```

```
#> Simple feature collection with 365 features and 7 fields
#> Geometry type: POINT
#> Dimension:      XY
#> Bounding box:  xmin: -445884.1 ymin: 1929616 xmax: -383656.8 ymax: 2061414
#> Projected CRS: NAD83 / Alaska Albers
#> # A tibble: 365 x 8
#>   log_Zn log_dist2road .fitted .resid   .hat .cooksd .std.resid
#> *   <dbl>          <dbl>   <dbl> <dbl>   <dbl>   <dbl>     <dbl>
#> 1    7.33          2.68    8.26 -0.928 0.0200 0.0142     1.18
#> 2    7.38          2.68    8.26 -0.880 0.0200 0.0186     1.35
#> 3    7.58          2.54    8.34 -0.755 0.0225 0.00482    0.647
#> 4    7.63          2.97    8.09 -0.464 0.0197 0.0305     1.74
#> 5    7.26          2.72    8.24 -0.977 0.0215 0.131      3.45
#> 6    7.65          2.76    8.21 -0.568 0.0284 0.0521     1.89
#> 7    7.59          2.30    8.47 -0.886 0.0300 0.0591     1.96
#> 8    7.16          2.78    8.20 -1.05  0.0335 0.00334    0.439
#> 9    7.19          2.93    8.12 -0.926 0.0378 0.0309     1.26
#> 10   8.07          2.79    8.20 -0.123 0.0314 0.00847    0.723
#> # ... with 355 more rows, and 1 more variable: geometry <POINT [m]>
```

By default, only the columns of data used to fit the model are returned alongside the diagnostics. All original columns of data are returned by setting `drop` to `FALSE`. `augment()` is especially powerful when the data are an `sf` object because model diagnostics can be easily visualized spatially. For example, we could subset the augmented object so that it only includes observations whose standardized residuals have absolute values greater than some cutoff and then visualize them spatially. To learn more about the broom functions for spatial linear models, run `help("tidy.splm", "splmodel")`, `help("glance.splm", "splmodel")`, and `help("augment.splm", "splmodel")`.

3.5 An Areal Data Example

Next we use the `seal` data, an `sf` object that contains the log of the estimated harbor-seal trends from abundance data across polygons in Alaska, to provide an example of fitting a spatial linear model for areal data using `spautor()`. We view the first few rows of `seal` by running

```
seal
```

```
#> Simple feature collection with 62 features and 1 field
#> Geometry type: POLYGON
#> Dimension:      XY
#> Bounding box:  xmin: 913618.8 ymin: 1007542 xmax: 1116002 ymax: 1145054
#> Projected CRS: NAD83 / Alaska Albers
#> # A tibble: 62 x 2
#>   log_trend geometry
#>   <dbl>      <POLYGON [m]>
#> 1 NA      ((1035002 1054710, 1035002 1054542, 1035002 1053542, 1035002 10525~
#> 2 -0.282   ((1037002 1039492, 1037006 1039490, 1037017 1039492, 1037035 10394~
#> 3 -0.00121 ((1070158 1030216, 1070185 1030207, 1070187 1030207, 1070211 10302~
#> 4  0.0354   ((1054906 1034826, 1054931 1034821, 1054936 1034822, 1055001 10348~
#> 5 -0.0160   ((1025142 1056940, 1025184 1056889, 1025222 1056836, 1025256 10567~
#> 6  0.0872   ((1026035 1044623, 1026037 1044605, 1026072 1044610, 1026083 10446~
#> 7 -0.266   ((1100345 1060709, 1100287 1060706, 1100228 1060706, 1100170 10607~
#> 8  0.0743   ((1030247 1029637, 1030248 1029637, 1030265 1029642, 1030328 10296~
#> 9 NA      ((1043093 1020553, 1043097 1020550, 1043101 1020550, 1043166 10205~
#> 10 -0.00961 ((1116002 1024542, 1116002 1023542, 1116002 1022542, 1116002 10215~
#> # ... with 52 more rows
```

We can learn more about the data by running `help("seal", "spmodel")`.

We can visualize the distribution of log seal trends in the `seal` data (Figure 3) by running

```
ggplot(seal, aes(fill = log_trend)) +
  geom_sf(size = 0.75) +
  scale_fill_viridis_c() +
  theme_bw(base_size = 14)
```

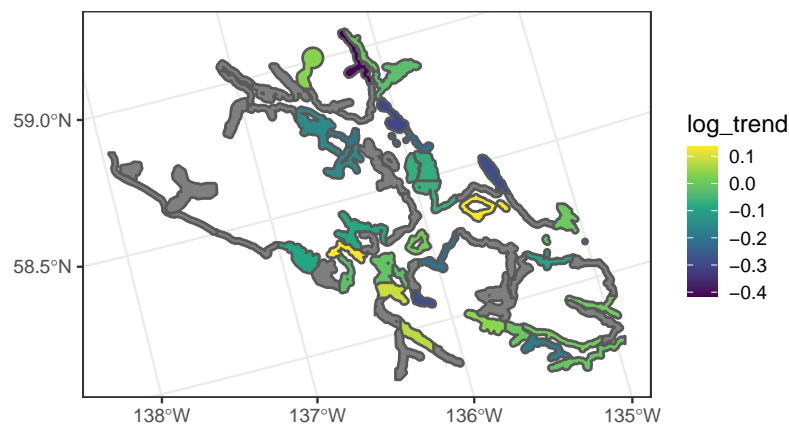


Figure 3: Distribution of log seal trends in the seal data. Polygons are gray if seal trends are missing.

Log trends can be viewed interactively in `mapview` by running

```
mapview(seal, zcol = "log_trend")
```

The gray polygons denote areas where the log trend is missing. These missing areas need to be kept in the data while fitting the model to preserve the overall neighborhood structure.

We estimate parameters of a spatial autoregressive model for log seal trends (`log_trend`) using an intercept-only model with a conditional autoregressive (CAR) spatial covariance by running

```
sealmod <- spautorm(log_trend ~ 1, seal, spcov_type = "car")
```

If a weight matrix is not provided to `spautorm()`, it is calculated internally using queen contiguity. Recall queen contiguity defines two observations as neighbors if they share at least one common boundary. If at least one observation has no neighbors, the `extra` parameter is estimated, which quantifies variability among observations without neighbors. By default, `spautorm()` uses row standardization (Ver Hoef et al. 2018) and assumes an independent error variance (`ie`) of zero.

We summarize, tidy, glance at, and augment the fitted model by running

```
summary(sealmod)
```

```
#>
#> Call:
#> spautorm(formula = log_trend ~ 1, data = seal, spcov_type = "car")
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -0.34441 -0.10403  0.04423  0.07351  0.20489
#>
#> Coefficients (fixed):
#>              Estimate Std. Error z value Pr(>|z|)
#> (Intercept) -0.07103      0.02492  -2.851  0.00436 **
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Coefficients (car spatial covariance):
#>      de  range  extra
#> 0.03226 0.42020 0.02235
```

```
tidy(sealmod)
```

```
#> # A tibble: 1 x 5
#>   term      estimate std.error statistic p.value
#>   <chr>      <dbl>    <dbl>    <dbl>    <dbl>
#> 1 (Intercept) -0.0710    0.0249    -2.85 0.00436
```

```
glance(sealmod)
```

```
#> # A tibble: 1 x 9
#>       n      p  npair value   AIC  AICc logLik deviance pseudo.r.squared
#>   <int> <dbl> <int> <dbl> <dbl> <dbl> <dbl>   <dbl>         <dbl>
#> 1    34     1     3  -36.9 -30.9 -30.1  18.4    33.2             0
```

```
augment(sealmod)
```

```
#> Simple feature collection with 34 features and 6 fields
#> Geometry type: POLYGON
#> Dimension: XY
#> Bounding box: xmin: 980001.5 ymin: 1010815 xmax: 1116002 ymax: 1145054
#> Projected CRS: NAD83 / Alaska Albers
#> # A tibble: 34 x 7
#>   log_trend .fitted .resid .hat .cooksd .std.resid geometry
```

```
#> *      <dbl>   <dbl>   <dbl>   <dbl>   <dbl>      <dbl>      <POLYGON [m]>
#> 1 -0.282   -0.0710  -0.211   0.0162  0.0211    -1.13  ((1037002 1039492, 10370~
#> 2 -0.00121 -0.0710   0.0698  0.0475  0.0260     0.722  ((1070158 1030216, 10701~
#> 3  0.0354   -0.0710   0.106   0.0292  0.0185     0.786  ((1054906 1034826, 10549~
#> 4 -0.0160   -0.0710   0.0550  0.0229  0.00160    0.262  ((1025142 1056940, 10251~
#> 5  0.0872   -0.0710   0.158   0.0277  0.0389     1.17  ((1026035 1044623, 10260~
#> 6 -0.266    -0.0710  -0.195   0.0278  0.0499    -1.32  ((1100345 1060709, 11002~
#> 7  0.0743   -0.0710   0.145   0.0493  0.0914     1.33  ((1030247 1029637, 10302~
#> 8 -0.00961 -0.0710   0.0614  0.0123  0.00245    0.445  ((1116002 1024542, 11160~
#> 9 -0.182    -0.0710  -0.111   0.0226  0.0226    -0.990  ((1079864 1025088, 10798~
#> 10  0.00351 -0.0710   0.0745  0.0317  0.0102     0.558  ((1110363 1037056, 11103~
#> # ... with 24 more rows
```

Note that for `spautorm()` models, the `ie` spatial covariance parameter is assumed zero by default (and omitted from the `summary()` output). This default behavior can be overridden by specifying `ie` in the `spcov_initial` argument to `spautorm()`. Also note that the pseudo R-squared is zero because there are no explanatory variables in the model (i.e., it is an intercept-only model).

4 Prediction

In this section, we show how to use `predict()` to perform spatial prediction (also called Kriging) in `spmodel`. We will fit a model using the point-referenced `sulfate` data, an `sf` object that contains sulfate measurements in the conterminous United States, and make predictions for each location in the point-referenced `sulfate_preds` data, an `sf` object that contains locations in the conterminous United States at which to predict sulfate.

We first visualize the distribution of the sulfate data (Figure 4, left) by running

```
ggplot(sulfate, aes(color = sulfate)) +
  geom_sf(size = 2.5) +
  scale_color_viridis_c(limits = c(0, 45)) +
  theme_gray(base_size = 18)
```

We then fit a spatial linear model for sulfate using an intercept-only model with a spherical spatial covariance function by running

```
sulfmod <- splm(sulfate ~ 1, sulfate, spcov_type = "spherical")
```

Then we obtain best linear unbiased predictions (Kriging predictions) using `predict()`, where the `newdata` argument contains the locations at which to predict, storing them as a new variable in `sulfate_preds` called `preds`:

```
sulfate_preds$preds <- predict(sulfmod, newdata = sulfate_preds)
```

We can visualize the model predictions (Figure 4, right) by running

```
ggplot(sulfate_preds, aes(color = preds)) +
  geom_sf(size = 2.5) +
  scale_color_viridis_c(limits = c(0, 45)) +
  theme_gray(base_size = 18)
```

Before making predictions, it is important to properly specify the `newdata` object. If explanatory variables were used to fit the model, the same explanatory variables must be included in `newdata` with the same names they have in `data`. Additionally, if an explanatory variable is categorical or a factor, the values of this variable in `newdata` must also be values in `data` (e.g., if a categorical variable with values "A", and "B" was used to fit the model, the corresponding variable in `newdata` cannot have a value "C"). If `data` is a `data.frame`, coordinates must be included in `newdata` with the same names as they have in `data`. If `data` is an `sf` object, coordinates must be included in `newdata` with the same geometry name as they have in `data`. When using

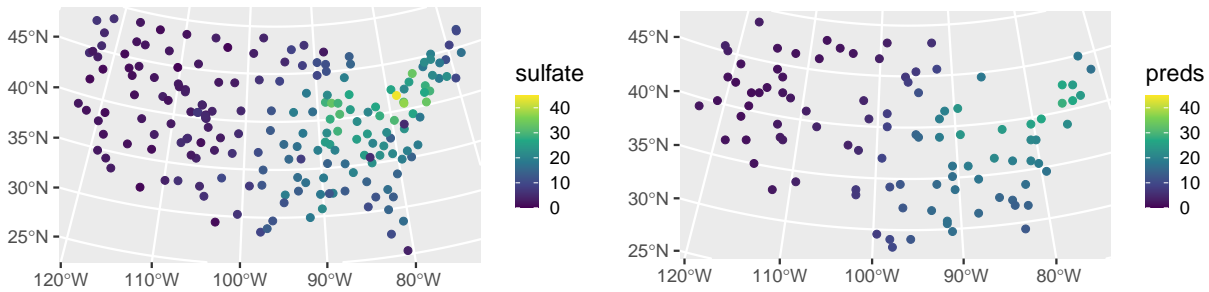


Figure 4: Distribution of observed sulfate (left) and sulfate predictions (right) in the conterminous United States.

projected coordinates, the projection for `newdata` should be the same as the projection for `data`.

Prediction standard errors are returned by setting the `se.fit` argument to `TRUE`:

```
predict(sulfmod, newdata = sulfate_preds, se.fit = TRUE)
```

The `interval` argument determines the type of interval returned. If `interval` is `"none"` (the default), no intervals are returned. If `interval` is `"prediction"`, `100 * level%` prediction intervals are returned (the default is 95% prediction intervals):

```
predict(sulfmod, newdata = sulfate_preds, interval = "prediction")
```

If `interval` is `"confidence"`, the predictions are instead the estimated mean given each observation's explanatory variable values. The corresponding `100 * level%` confidence intervals are returned:

```
predict(sulfmod, newdata = sulfate_preds, interval = "confidence")
```

Previously we used the `augment()` function to augment `data` with model diagnostics. We can also use `augment()` as an alternative to `predict()` to augment `newdata` with predictions, standard errors, and intervals. We remove the model predictions from `sulfate_preds` before showing how `augment()` is used to obtain the same predictions by running

```
sulfate_preds$preds <- NULL
```

We then view the first few rows of `sulfate_preds` augmented with 90% prediction intervals by running

```
augment(sulfmod, newdata = sulfate_preds, interval = "prediction", level = 0.90)
```

```
#> Simple feature collection with 100 features and 3 fields
#> Geometry type: POINT
#> Dimension:      XY
#> Bounding box:  xmin: -2283774 ymin: 582930.5 xmax: 1985906 ymax: 3037173
#> Projected CRS: NAD83 / Conus Albers
#> # A tibble: 100 x 4
#>   .fitted .lower .upper      geometry
#>   *   <dbl> <dbl> <dbl>      <POINT [m]>
#> 1     1.40 -5.33  8.14  (-1771413 1752976)
#> 2    24.5  18.2  30.8   (1018112 1867127)
#> 3     8.99  2.36 15.6  (-291256.8 1553212)
#> 4    16.4   9.92 23.0   (1274293 1267835)
```

```
#> 5    4.91 -1.56 11.4 (-547437.6 1638825)
#> 6   26.7 20.4 33.0 (1445080 1981278)
#> 7    3.00 -3.65 9.66 (-1629090 3037173)
#> 8   14.3 7.97 20.6 (1302757 1039534)
#> 9    1.49 -5.08 8.06 (-1429838 2523494)
#> 10  14.4 7.97 20.8 (1131970 1096609)
#> # ... with 90 more rows
```

Here, `.fitted` represents the predictions.

An alternative (but equivalent) approach can be used for model fitting and prediction that circumvents the need to keep `data` and `newdata` as separate objects. Suppose that observations requiring prediction are stored in `data` as missing (NA) values. We can add a column of missing values to `sulfate_preds` and then bind it together with `sulfate` by running

```
sulfate_preds$sulfate <- NA
sulfate_with_NA <- rbind(sulfate, sulfate_preds)
```

We can then fit a spatial linear model by running

```
sulfmod_with_NA <- splm(sulfate ~ 1, sulfate_with_NA, "spherical")
```

The missing values are ignored for model-fitting but stored in `sulfmod_with_NA` as `newdata`:

```
sulfmod_with_NA$newdata
```

```
#> Simple feature collection with 100 features and 1 field
#> Geometry type: POINT
#> Dimension:      XY
#> Bounding box:  xmin: -2283774 ymin: 582930.5 xmax: 1985906 ymax: 3037173
#> Projected CRS: NAD83 / Conus Albers
#> First 10 features:
#>    sulfate      geometry
#> 198      NA POINT (-1771413 1752976)
#> 199      NA POINT (1018112 1867127)
#> 200      NA POINT (-291256.8 1553212)
#> 201      NA POINT (1274293 1267835)
#> 202      NA POINT (-547437.6 1638825)
#> 203      NA POINT (1445080 1981278)
#> 204      NA POINT (-1629090 3037173)
#> 205      NA POINT (1302757 1039534)
#> 206      NA POINT (-1429838 2523494)
#> 207      NA POINT (1131970 1096609)
```

We can then predict the missing values by running

```
predict(sulfmod_with_NA)
```

The call to `predict()` finds in `sulfmod_with_NA` the `newdata` object and is equivalent to

```
predict(sulfmod_with_NA, newdata = sulfmod_with_NA$newdata)
```

We can also use `augment()` to make the predictions on the data set with missing values by running

```
augment(sulfmod_with_NA, newdata = sulfmod_with_NA$newdata)
```

```
#> Simple feature collection with 100 features and 2 fields
#> Geometry type: POINT
#> Dimension:      XY
#> Bounding box:  xmin: -2283774 ymin: 582930.5 xmax: 1985906 ymax: 3037173
```

```
#> Projected CRS: NAD83 / Conus Albers
#> # A tibble: 100 x 3
#>   sulfate .fitted geometry
#> *   <dbl>   <dbl>   <POINT [m]>
#> 1      NA     1.40 (-1771413 1752976)
#> 2      NA    24.5  (1018112 1867127)
#> 3      NA     8.99 (-291256.8 1553212)
#> 4      NA    16.4  (1274293 1267835)
#> 5      NA     4.91 (-547437.6 1638825)
#> 6      NA    26.7  (1445080 1981278)
#> 7      NA     3.00 (-1629090 3037173)
#> 8      NA    14.3  (1302757 1039534)
#> 9      NA     1.49 (-1429838 2523494)
#> 10     NA    14.4  (1131970 1096609)
#> # ... with 90 more rows
```

Unlike `predict()`, `augment()` explicitly requires the `newdata` argument be specified in order to obtain predictions. Omitting `newdata` (e.g., running `augment(sulfmod_with_NA)`) returns model diagnostics, not predictions.

For areal data models fit with `spautor()`, predictions cannot be computed at locations that were not incorporated in the neighborhood structure used to fit the model. Thus, predictions are only possible for observations in `data` whose response values are missing (NA), as their locations are incorporated into the neighborhood structure. For example, we make predictions of log seal trends at the missing polygons from Figure 3 by running

```
predict(sealmod)
```

We can also use `augment()` to make the predictions:

```
augment(sealmod, newdata = sealmod$newdata)
```

```
#> Simple feature collection with 28 features and 2 fields
#> Geometry type: POLYGON
#> Dimension: XY
#> Bounding box: xmin: 913618.8 ymin: 1007542 xmax: 1115097 ymax: 1132682
#> Projected CRS: NAD83 / Alaska Albers
#> # A tibble: 28 x 3
#>   log_trend .fitted geometry
#> *   <dbl>   <dbl>   <POLYGON [m]>
#> 1      NA -0.115 ((1035002 1054710, 1035002 1054542, 1035002 1053542, 1035~
#> 2      NA -0.00918 ((1043093 1020553, 1043097 1020550, 1043101 1020550, 1043~
#> 3      NA -0.0603 ((1099737 1054310, 1099752 1054262, 1099788 1054278, 1099~
#> 4      NA -0.0360 ((1099002 1036542, 1099134 1036462, 1099139 1036431, 1099~
#> 5      NA -0.0724 ((1076902 1053189, 1076912 1053179, 1076931 1053179, 1076~
#> 6      NA -0.0549 ((1070501 1046969, 1070317 1046598, 1070308 1046542, 1070~
#> 7      NA -0.0976 ((1072995 1054942, 1072996 1054910, 1072997 1054878, 1072~
#> 8      NA -0.0715 ((960001.5 1127667, 960110.8 1127542, 960144.1 1127495, 9~
#> 9      NA -0.0825 ((1031308 1079817, 1031293 1079754, 1031289 1079741, 1031~
#> 10     NA -0.0593 ((998923.7 1053647, 998922.5 1053609, 998950 1053631, 999~
#> # ... with 18 more rows
```

5 Advanced Features

`spmodel` offers several advanced features for fitting spatial linear models. We briefly discuss some of these features next using the `moos` data, the `moose` data, and some simulated data. Technical details for each

advanced feature can be seen by running `vignette("technical", "spmodel")`.

5.1 Fixing Spatial Covariance Parameters

We may desire to fix specific spatial covariance parameters at a particular value. Perhaps some parameter value is known, for example. Or perhaps we want to compare nested models where a reduced model uses a fixed parameter value while the full model estimates the parameter. Fixing spatial covariance parameters while fitting a model is possible using the `spcov_initial` argument to `splm()` and `spautor()`. The `spcov_initial` argument takes an `spcov_initial` object (run `help("spcov_initial", "spmodel")` for more). `spcov_initial` objects can also be used to specify initial values used during optimization, even if they are not assumed to be fixed. By default, `spmodel` uses a grid search to find suitable initial values to use during optimization.

As an example, suppose our goal is to compare a model with an exponential covariance with dependent error variance, independent error variance, and range parameters to a model that assumes the independent random error variance parameter (nugget) is zero. First, the `spcov_initial` object is specified for the latter model:

```
init <- spcov_initial("exponential", ie = 0, known = "ie")
print(init)
```

```
#> $initial
#> ie
#> 0
#>
#> $is_known
#> ie
#> TRUE
#>
#> attr(,"class")
#> [1] "exponential"
```

The `init` output shows that the `ie` parameter has an initial value of zero that is assumed to be known. Next the model is fit:

```
spmod_red <- splm(log_Zn ~ log_dist2road, moss, spcov_initial = init)
```

Notice that because the `spcov_initial` object contains information about the spatial covariance type, the `spcov_type` argument is not required when `spcov_initial` is provided. We can use `glances()` to glance at both models:

```
glances(spmod, spmod_red)
```

```
#> # A tibble: 2 x 10
#>   model      n      p  npar value   AIC   AICc logLik deviance pseudo.r.squared
#>   <chr>    <int> <dbl> <int> <dbl> <dbl> <dbl> <dbl>    <dbl>
#> 1 spmod    365     2     3  367.  373.  373.  -184.    363.      0.683
#> 2 spmod_red 365     2     2  378.  382.  382.  -189.    374.      0.703
```

The lower AIC and AICc of the full model compared to the reduced model indicates that the independent random error variance is important to the model. A likelihood ratio test comparing the full and reduced models is also possible using `anova()`.

Another application of fixing spatial covariance parameters involves calculating their profile likelihood confidence intervals (Box and Cox 1964). Before calculating a profile likelihood confidence interval for Θ_i , the i th element of a general parameter vector Θ , it is necessary to obtain $-2\ell(\hat{\Theta})$, minus twice the log-likelihood evaluated at the estimated parameter vector, $\hat{\Theta}$. Then a $(1 - \alpha)\%$ profile likelihood confidence interval is the set of values for Θ_i such that $2\ell(\hat{\Theta}) - 2\ell(\hat{\Theta}_{-i}) \leq \chi^2_{1,1-\alpha}$, where $\ell(\hat{\Theta}_{-i})$ is the value of the log-likelihood maximized after fixing Θ_i and optimizing over the remaining parameters, Θ_{-i} , and $\chi^2_{1,1-\alpha}$ is the $1 - \alpha$

quantile of a chi-squared distribution with one degree of freedom. The result follows from inverting a likelihood ratio test comparing the full model to a reduced model that fixes the value of Θ_i . Because this approach requires refitting the model many times for different fixed values of Θ_i , it can be computationally intensive. This approach can be generalized to yield joint profile likelihood confidence intervals cases when i has dimension greater than one.

5.2 Fitting and Predicting for Multiple Models

Fitting multiple models is possible with a single call to `splm()` or `spautor()` when `spcov_type` is a vector with length greater than one or `spcov_initial` is a list (with length greater than one) of `spcov_initial` objects (Section 5.1). We fit three separate spatial linear models using the exponential spatial covariance, spherical spatial covariance, and no spatial covariance by running

```
spmods <- splm(sulfate ~ 1, sulfate, spcov_type = c("exponential", "spherical", "none"))
```

`spmods` is list whose names indicate the spatial covariance type and whose values indicate the model fit for that spatial covariance type. Generic functions can be called individually for each list element. For example, we can augment the the model fit using the exponential covariance function with diagnostics by running

```
augment(spmods$exponential)
```

```
#> Simple feature collection with 197 features and 6 fields
#> Geometry type: POINT
#> Dimension: XY
#> Bounding box: xmin: -2292550 ymin: 386181.1 xmax: 2173345 ymax: 3090370
#> Projected CRS: NAD83 / Conus Albers
#> # A tibble: 197 x 7
#>   sulfate .fitted .resid .hat .cooksd .std.resid geometry
#> *   <dbl> <dbl> <dbl> <dbl> <dbl> <dbl> <POINT [m]>
#> 1 12.9      5.92  7.00 0.00334 0.00161 -0.694 (817738.8 1080571)
#> 2 20.2      5.92 14.2 0.00256 0.00192  0.865 (914593.6 1295545)
#> 3 16.8      5.92 10.9 0.00259 0.000395  0.390 (359574.1 1178228)
#> 4 16.2      5.92 10.3 0.00239 0.000363  0.390 (265331.9 1239089)
#> 5  7.86      5.92  1.93 0.00202 0.00871 -2.07 (304528.8 1453636)
#> 6 15.4      5.92  9.43 0.00201 0.000240  0.345 (162932.8 1451625)
#> 7  0.986      5.92 -4.94 0.00380 0.000966 -0.503 (-1437776 1568022)
#> 8  0.425      5.92 -5.50 0.0138 0.00584 -0.646 (-1572878 1125529)
#> 9  3.58      5.92 -2.34 0.00673 0.0000148 -0.0467 (-1282009 1204889)
#> 10 2.38      5.92 -3.54 0.0123 0.0000139 -0.0335 (-1972775 1464991)
#> # ... with 187 more rows
```

Or we can find the AIC of the model fit using the spherical covariance function by running

```
AIC(spmods$spherical)
```

```
#> [1] 1143.202
```

The `glances()` and `predict()` functions can work directly with `spmods`, calling `glances()` and `predict()` on each list element and then organizing the results. We glance at each fitted model object by running

```
glances(spmods)
```

```
#> # A tibble: 3 x 10
#>   model      n      p  npar value   AIC  AICc logLik deviance pseudo.r.squared
#>   <chr>   <int> <dbl> <int> <dbl> <dbl> <dbl> <dbl>   <dbl>         <dbl>
#> 1 spherical  197     1     3 1137. 1143. 1143.  -569.    196.             0
#> 2 exponent~  197     1     3 1140. 1146. 1146.  -570.    196.             0
#> 3 none      197     1     1 1448. 1450. 1450.  -724.    196             0
```

We predict `newdata` separately for each fitted model object by running

```
predict(spmods, newdata = sulfate_preds)
```

5.3 Random Effects

Non-spatial random effects incorporate additional sources of variability into model fitting. They are accommodated in `spmodel` using similar syntax as for random effects in the `nlme` (Pinheiro and Bates 2006) and `lme4` (Bates et al. 2015) **R** packages. Random effects are specified via a formula passed to the `random` argument. Next we show two examples that incorporate random effects into the spatial linear model using the `moss` data.

The first example explores random intercepts for the `sample` variable. The `sample` variable indexes each unique location, which can have replicate observations due to field duplicates (`field_dup`) and lab replicates (`lab_rep`). There are 365 observations in `moss` at 318 unique locations, which means that 47 observations in `moss` are either field duplicates or lab replicates. It is likely that the repeated observations at a location are correlated with one another. We can incorporate this repeated-observation correlation by creating a random intercept for each level of `sample`. We model the random intercepts for `sample` by running

```
rand1 <- splm(  
  log_Zn ~ log_dist2road,  
  moss,  
  spcov_type = "exponential",  
  random = ~ sample  
)
```

Note that `~ sample` is shorthand for `(1 | sample)`, which is more explicit notation that indicates random intercepts for each level of `sample`.

The second example adds a random intercept for `year`, which creates extra correlation for observations within a year. It also adds a random slope for `log_dist2road` within `year`, which lets the effect of `log_dist2road` vary between years. We fit this model by running

```
rand2 <- splm(  
  log_Zn ~ log_dist2road,  
  moss,  
  spcov_type = "exponential",  
  random = ~ sample + (log_dist2road | year)  
)
```

Note that `sample + (log_dist2road | year)` is shorthand for `(1 | sample) + (log_dist2road | year)`. If only random slopes within a year are desired (and no random intercepts), a `- 1` is given to the relevant portion of the formula: `(log_dist2road - 1 | year)`. When there is more than one term in `random`, each term must be surrounded by parentheses (recall that the random intercept shorthand automatically includes relevant parentheses). More examples of random effect syntax are provided in Appendix B.

We compare the AIC of the models by running

```
glances(rand1, rand2)
```

```
#> # A tibble: 2 x 10  
#>   model      n      p  npar value    AIC  AICc logLik deviance pseudo.r.squared  
#>   <chr> <int> <dbl> <int> <dbl> <dbl> <dbl> <dbl>    <dbl>         <dbl>  
#> 1 rand2  365     2     6  190.  202.  202.  -94.9    363.         0.215  
#> 2 rand1  365     2     4  335.  343.  343. -168.    363.         0.661
```

The `rand2` model has the lowest AIC.

It is possible to fix random effect variances using the `randcov_initial` argument, and `randcov_initial` can also be used to set initial values for optimization.

5.4 Partition Factors

A partition factor is a variable that allows observations to be uncorrelated when they are from different levels of the partition factor. Partition factors are specified in `splm` by providing a formula with a single variable to the `partition_factor` argument. Suppose that for the `mooss` data, we want observations in different years (`year`) to be uncorrelated. We fit a model that treats year as a partition factor by running

```
part <- splm(
  log_Zn ~ log_dist2road,
  mooss,
  spcov_type = "exponential",
  partition_factor = ~ year
)
```

5.5 Anisotropy

An isotropic spatial covariance function (for point-referenced data) behaves similarly in all directions (i.e., is independent of direction) as a function of distance. An anisotropic covariance function does not behave similarly in all directions as a function of distance. Consider the spatial covariance imposed by an eastward-moving wind pattern. A one-unit distance in the x-direction likely means something different than a one-unit distance in the y-direction. Figure 5 shows ellipses for an isotropic and anisotropic covariance function centered at the origin (a distance of zero).

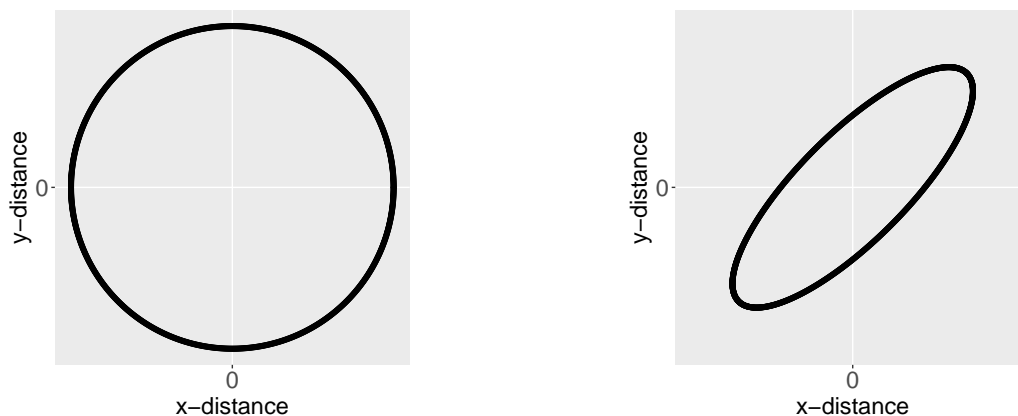


Figure 5: Ellipses for an isotropic (left) and anisotropic (right) covariance function centered at the origin. The black outline of each ellipse is a level curve of equal correlation.

The black outline of each ellipse is a level curve of equal correlation. The left ellipse (a circle) represents an isotropic covariance function. The distance at which the correlation between two observations lays on the level curve is the same in all directions. The right ellipse represents an anisotropic covariance function. The distance at which the correlation between two observations lays on the level curve is different in different directions.

Accounting for anisotropy involves a rotation and scaling of the x-coordinates and y-coordinates such that the spatial covariance function that uses these transformed distances is isotropic. We use the `anisotropy` argument to `splm()` to fit a model with anisotropy by running

```
splmod_anis <- splm(
  log_Zn ~ log_dist2road,
```

```

    moss,
    spcov_type = "exponential",
    anisotropy = TRUE
)
summary(splm_anis)

#>
#> Call:
#> splm(formula = log_Zn ~ log_dist2road, data = moss, spcov_type = "exponential",
#>       anisotropy = TRUE)
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -2.5279 -1.2239 -0.7202 -0.1921  1.1659
#>
#> Coefficients (fixed):
#>              Estimate Std. Error z value Pr(>|z|)
#> (Intercept)   9.54798    0.22291   42.83   <2e-16 ***
#> log_dist2road -0.54601    0.01855  -29.44   <2e-16 ***
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Pseudo R-squared:  0.7048
#>
#> Coefficients (exponential spatial covariance):
#>      de      ie    range  rotate    scale
#> 3.561e-01 6.812e-02 8.732e+03 2.435e+00 4.753e-01
#> attr("class")
#> [1] "exponential"

```

The `rotate` parameter is between zero and π radians and represents the angle of a clockwise rotation of the ellipse such that the major axis of the ellipse is the new x-axis and the minor axis of the ellipse is the new y-axis. The `scale` parameter is between zero and one and represents the ratio of the distance between the origin and the edge of the ellipse along the minor axis to the distance between the origin and the edge of the ellipse along the major axis. Figure 6 shows a transformation that turns an anisotropic ellipse into an isotropic one (i.e., a circle). This transformation requires rotating the coordinates clockwise by `rotate` and then scaling them the reciprocal of `scale`. The transformed coordinates are then used instead of the original coordinates to compute distances and spatial covariances.

Note that specifying an initial value for `rotate` that is different from zero, specifying an initial value for `scale` that is different from one, or assuming either `rotate` or `scale` are unknown in `spcov_initial` will cause `splm()` to fit a model with anisotropy (and will override `anisotropy = FALSE`). Estimating anisotropy parameters is only possible for maximum likelihood and restricted maximum likelihood estimation, but fixed anisotropy parameters can be accommodated for semivariogram weighted least squares or semivariogram composite likelihood estimation. Also note that anisotropy is not relevant for areal data because the spatial covariance function depends on a neighborhood structure instead of distances between points.

5.6 Simulating Spatial Data

The `sprnorm()` function is used to simulate normal (Gaussian) spatial data. To use `sprnorm()`, the `spcov_params()` function is used to create an `spcov_params` object. The `spcov_params()` function requires the spatial covariance type and parameter values. We create an `spcov_params` object by running

```
sim_params <- spcov_params("exponential", de = 5, ie = 1, range = 0.5)
```

We set a reproducible seed and then simulate data at 3000 random locations in the unit square using the

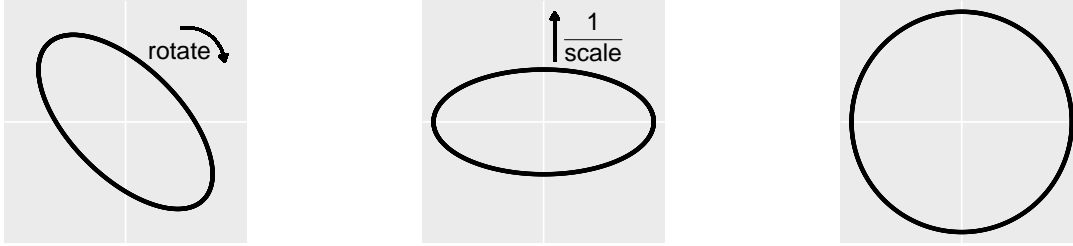


Figure 6: A visual representation of the anisotropy transformation. In the left figure, the first step is to rotate the anisotropic ellipse clockwise by the `rotate` parameter (here `rotate` is 0.75π radians or 135 degrees). In the middle figure, the second step is to scale the y axis by the reciprocal of the `scale` parameter (here `scale` is 0.5). In the right figure, the anisotropic ellipse has been transformed into an isotropic one (i.e., a circle). The transformed coordinates are then used instead of the original coordinates to compute distances and spatial covariances.

spatial covariance parameters in `sim_params` by running

```
set.seed(0)
n <- 3000
x <- runif(n)
y <- runif(n)
sim_coords <- tibble::tibble(x, y)
sim_response <- sprnorm(sim_params, data = sim_coords, xcoord = x, ycoord = y)
sim_data <- tibble::tibble(sim_coords, sim_response)
```

We can visualize the simulated data (Figure 7, left) by running

```
ggplot(sim_data, aes(x = x, y = y, color = sim_response)) +
  geom_point(size = 1.5) +
  scale_color_viridis_c(limits = c(-7, 7)) +
  theme_gray(base_size = 18)
```

There is noticeable spatial patterning in the response variable (`sim_response`). The default mean in `sprnorm()` is zero for all observations, though a mean vector can be provided using the `mean` argument. The default number of samples generated in `sprnorm()` is one, though this can be changed using the `samples` argument. Because `sim_data` is a `tibble` (`data.frame`) and not an `sf` object, the columns in `sim_data` representing the x-coordinates and y-coordinates must be provided to `sprnorm()`.

Note that the output from `coef(object, type = "spcov")` is a `spcov_params` object. This is useful if we want to simulate data given the estimated spatial covariance parameters from a fitted model. Random effects are incorporated into simulation via the `randcov_params` argument.

5.7 Big Data

The computational cost associated with model fitting is exponential in the sample size for all estimation methods. For maximum likelihood and restricted maximum likelihood, the computational cost of estimating θ is cubic. For semivariogram weighted least squares and semivariogram composite likelihood, the computational cost of estimating θ is quadratic. The computational cost associated with estimating β and prediction is cubic, regardless of estimation method. Typically, samples sizes approaching 10,000 make the computational cost of model fitting and prediction infeasible, which necessitates the use of big data methods. `splm` offers big data methods for model fitting of point-referenced data via the `local` argument to `splm()`. The method is capable of quickly fitting models with hundreds of thousands of observations. Because of the neighborhood structure of areal data, the big data methods used for point-referenced data do not apply to areal data. Thus,

there is no big data method for areal data or `local` argument to `spautoc()`, so model fitting sample sizes cannot be too large

`spmodel` offers big data methods for prediction of point-referenced data or areal data via the `local` argument to `predict()`. This method is capable of quickly predicting hundreds of thousands of observations. To show how to use `spmodel` for big data estimation and prediction, we use the `sim_data` data from Section 5.6. Because `sim_data` is a `tibble` (`data.frame`) and not an `sf` object, the columns in `data` representing the x-coordinates and y-coordinates must be explicitly provided to `splm()`.

Next we briefly discuss model fitting and prediction for big data in `spmodel`, but further details are provided by Ver Hoef, Dumelle, et al. (2023).

5.7.1 Model Fitting

`spmodel` uses a “local spatial indexing” (SPIN) approach for big data model fitting of point-referenced data. Observations are first assigned an index. Then for the purposes of model fitting, observations with different indexes are assumed uncorrelated. Assuming observations with different indexes are uncorrelated induces sparsity in the covariance matrix, which greatly reduces the computational time of operations that involve the covariance matrix.

The `local` argument to `splm()` controls the big data options. `local` is a list with several arguments. The arguments to the `local` list control the method used to assign the indexes, the number of observations with the same index, the number of unique indexes, variance adjustments to the covariance matrix of $\hat{\beta}$, whether or not to use parallel processing, and if parallel processing is used, the number of cores.

Big data are most simply accommodated by setting `local` to `TRUE`. This is shorthand for

```
local = list(method = "random", size = 50, var_adjust = "theoretical", parallel = FALSE),
```

which randomly assigns observations to index groups, ensures each index group has approximately 50 observations, uses the theoretically-correct variance adjustment, and does not use parallel processing.

```
local1 <- splm(sim_response ~ 1, sim_data, spcov_type = "exponential",
               xcoord = x, ycoord = y, local = TRUE)
summary(local1)
```

```
#>
#> Call:
#> splm(formula = sim_response ~ 1, data = sim_data, spcov_type = "exponential",
#>       xcoord = x, ycoord = y, local = TRUE)
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -5.0356 -1.3514 -0.1468  1.2842  6.5381
#>
#> Coefficients (fixed):
#>              Estimate Std. Error z value Pr(>|z|)
#> (Intercept)   -1.021      0.699   -1.46   0.144
#>
#> Coefficients (exponential spatial covariance):
#>      de      ie  range
#> 2.8724 0.9735 0.2644
```

Instead of using `local = TRUE`, we can explicitly set `local`. For example, we can fit a model using k-means clustering (MacQueen 1967) on the x-coordinates and y-coordinates to create 60 groups (clusters), use the pooled variance adjustment, and use parallel processing with two cores by running

```
local2_list <- list(method = "kmeans", groups = 60, var_adjust = "pooled",
                    parallel = TRUE, ncores = 2)
```

```
local2 <- splm(sim_response ~ 1, sim_data, spcov_type = "exponential",
              xcoord = x, ycoord = y, local = local2_list)
```

Likelihood-based statistics like `AIC()`, `AICc()`, `logLik()`, and `deviance()` should not be used to compare a model fit with a big data approximation to a model fit without a big data approximation, as the two approaches maximize different likelihoods.

5.7.2 Prediction

For point-referenced data, `splm` uses a “local neighborhood” approach for big data prediction. Each prediction is computed using a subset of the observed data instead of all of the observed data. Before further discussing big data prediction, we simulate 1000 locations in the unit square requiring prediction:

```
n_pred <- 1000
x <- runif(n_pred)
y <- runif(n_pred)
sim_preds <- tibble::tibble(x = x, y = y)
```

The `local` argument to `predict()` controls the big data options. `local` is a list with several arguments. The arguments to the `local` list control the method used to subset the observed data, the number of observations in each subset, whether or not to use parallel processing, and if parallel processing is used, the number of cores.

The simplest way to accommodate big data prediction is to set `local` to `TRUE`. This is shorthand for `local = list(method = "covariance", size = 50, parallel = FALSE)`, which implies that, for each location requiring prediction, only the 50 observations in the data most correlated with it are used in the computation and parallel processing is not used. Using the `local1` fitted model, we store these predictions as a variable called `preds` in the `sim_preds` data by running

```
sim_preds$preds <- predict(local1, newdata = sim_preds, local = TRUE)
```

The predictions are visualized (Figure 7, right) by running

```
ggplot(sim_preds, aes(x = x, y = y, color = preds)) +
  geom_point(size = 1.5) +
  scale_color_viridis_c(limits = c(-7, 7)) +
  theme_gray(base_size = 18)
```

They display a similar pattern as the observed data.

Instead of using `local = TRUE`, we can explicitly set `local`:

```
pred_list <- list(method = "distance", size = 30, parallel = TRUE, ncores = 2)
predict(local1, newdata = sim_preds, local = pred_list)
```

This code implies that uniquely for each location requiring prediction, only the 30 observations in the data closest to it (in terms of Euclidean distance) are used in the computation and parallel processing is used with two cores.

For areal data, no local neighborhood approximation exists because of the data’s underlying neighborhood structure. Thus, all of the data must be used to compute predictions, and by consequence, `method` and `size` are not components of the `local` list. The only components of the `local` list for areal data are `parallel` and `ncores`.

5.8 Random Forest Spatial Residual Models

Random forest spatial residual models are used for prediction. They combine aspects of random forest prediction and spatial linear model prediction, which can lead to significant improvements in predictive accuracy compared to standard random forest prediction (Fox, Ver Hoef, and Olsen 2020). To fit a random

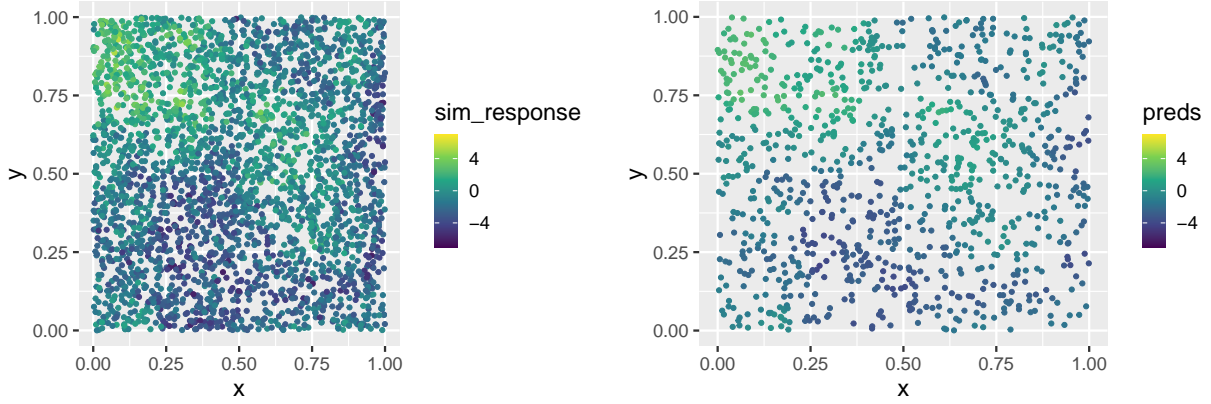


Figure 7: Observed data and big data predictions at unobserved locations. In the left figure, spatial data are simulated in the unit square. A spatial linear model is fit using the default big data approximation for model-fitting. In the right figure, predictions are made using the fitted model and the default big data approximation for prediction.

forest spatial residual model, use `splmRF()` (for point-referenced data) or `spautorRF()` (for areal data). These functions require at least one explanatory variable be specified, so we add an explanatory variable called `var` to `sulfate` and `sulfate_preds` for illustrative purposes.

```
sulfate$var <- rnorm(NROW(sulfate))
sulfate_preds$var <- rnorm(NROW(sulfate_preds))
```

Then we fit a random forest spatial residual model by running

```
sprfmod <- splmRF(sulfate ~ var, sulfate, spcov_type = "exponential")
```

And we make predictions by running

```
predict(sprfmod, newdata = sulfate_preds)
```

5.9 Spatial Generalized Linear Models

When building spatial linear models, the response vector \mathbf{y} is typically assumed Gaussian (given \mathbf{X}). Relaxing this assumption on the distribution of \mathbf{y} yields a rich class of spatial generalized linear models that can describe binary data, proportion data, count data, and skewed data that is parameterized as

$$g(\boldsymbol{\mu}) = \boldsymbol{\eta} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\tau} + \boldsymbol{\epsilon}, \quad (3)$$

where $g(\cdot)$ is called a link function, $\boldsymbol{\mu}$ is the mean of \mathbf{y} , and the remaining terms \mathbf{X} , $\boldsymbol{\beta}$, $\boldsymbol{\tau}$, $\boldsymbol{\epsilon}$ represent the same quantities as for the spatial linear models (Section 2). The link function, $g(\cdot)$, “links” a function of $\boldsymbol{\mu}$ to the linear term $\boldsymbol{\eta}$, denoted here as $\mathbf{X}\boldsymbol{\beta} + \boldsymbol{\tau} + \boldsymbol{\epsilon}$, which is familiar from spatial linear models. Note that the linking of $\boldsymbol{\mu}$ to $\boldsymbol{\eta}$ applies element-wise to each vector. Each link function $g(\cdot)$ has a corresponding inverse link function, $g^{-1}(\cdot)$. The inverse link function “links” a function of $\boldsymbol{\eta}$ to $\boldsymbol{\mu}$. Notice that for spatial generalized linear models, we are not modeling \mathbf{y} directly as we do for spatial linear models, but rather we are modeling a function of the mean of \mathbf{y} . Also notice that $\boldsymbol{\eta}$ is unconstrained but $\boldsymbol{\mu}$ is usually constrained in some way (e.g., positive).

Equation 3 is called the spatial generalized linear model. `spmodel` allows fitting of spatial generalized linear models when \mathbf{y} is a binomial (or Bernoulli), beta, Poisson, negative binomial, gamma, or inverse Gaussian random vector via the Laplace approximation and restricted maximum likelihood estimation or maximum likelihood estimation – Ver Hoef, Blagg, et al. (2023) provide further details. For binomial and beta \mathbf{y} , the logit link function is defined as $g(\boldsymbol{\mu}) = \ln(\frac{\boldsymbol{\mu}}{1-\boldsymbol{\mu}}) = \boldsymbol{\eta}$, and the inverse logit link function is defined as

$g^{-1}(\eta) = \frac{\exp(\eta)}{1+\exp(\eta)} = \mu$. For Poisson, negative binomial, gamma, and inverse Gaussian \mathbf{y} , the log link function is defined as $g(\mu) = \ln(\mu) = \eta$, and the inverse log link function is defined as $g^{-1}(\eta) = \exp(\eta) = \mu$. Full parameterizations of these distributions are given in the technical details vignette, which can be viewed by running `vignette("technical", "spmodel")`.

All advanced features available in `spmodel` for spatial linear models are also available for spatial generalized linear models. This means that spatial generalized linear models in `spmodel` can accommodate fixing spatial covariance parameters, fitting and predicting for multiple models, random effects (on the link scale), partition factors, anisotropy (on the link scale), simulation, big data, and prediction.

5.9.1 Model Fitting

As with spatial linear models, spatial generalized linear models are fit in `spmodel` for point-referenced and areal data. The `spglm()` function is used to fit spatial generalized linear models for point-referenced data, and the `spgautor()` function is used to fit spatial generalized linear models for areal data. `spglm()` and `spgautor()` share similar syntax with `splm()` and `spautor()`, respectively, though one additional argument is required:

- **family**: the generalized linear model family (i.e., the distribution of \mathbf{y}). **family** can be `binomial`, `beta`, `poisson`, `nbinomial`, `Gamma`, or `inverse.gaussian`.
 - **family** uses similar syntax as the **family** argument in `glm()`.
 - One difference between **family** in `spglm()` compared to **family** in `glm()` is that the link function is fixed in `spglm()`.

As with `splm()` and `spautor()`, the data argument to `spglm()` and `spgautor()` can be an `sf` object or `data.frame` (with appropriate coordinate or weight matrix information). Additionally, all arguments to `splm()` and `spautor()` are also available for `spglm()` and `spgautor()`.

Next we show the basic features and syntax of `spglm()` using the `moose` data. We study the impact of elevation (`elev`) on the presence of moose (`presence`) observed at a site location in Alaska. `presence` equals one if at least one moose was observed at the site and zero otherwise. We view the first few rows of the `moose` data by running

```
moose

#> Simple feature collection with 218 features and 4 fields
#> Geometry type: POINT
#> Dimension:      XY
#> Bounding box:   xmin: 269085 ymin: 1416151 xmax: 419976.2 ymax: 1541763
#> Projected CRS: NAD83 / Alaska Albers
#> First 10 features:
#>      elev strat count presence      geometry
#> 1  468.9167    L     0         0 POINT (293542.6 1541016)
#> 2  362.3125    L     0         0 POINT (298313.1 1533972)
#> 3  172.7500    M     0         0 POINT (281896.4 1532516)
#> 4  279.6250    L     0         0 POINT (298651.3 1530264)
#> 5  619.6000    L     0         0 POINT (311325.3 1527705)
#> 6  164.1250    M     0         0 POINT (291421.5 1518398)
#> 7  163.5000    M     0         0 POINT (287298.3 1518035)
#> 8  186.3500    L     0         0 POINT (279050.9 1517324)
#> 9  362.3125    L     0         0 POINT (346145.9 1512479)
#> 10 430.5000    L     0         0 POINT (321354.6 1509966)
```

We can visualize the distribution of moose presence (`presence`) by running

```
ggplot(moose, aes(color = presence)) +
  geom_sf(size = 2) +
```

```
scale_color_viridis_d() +
theme_gray(base_size = 14)
```

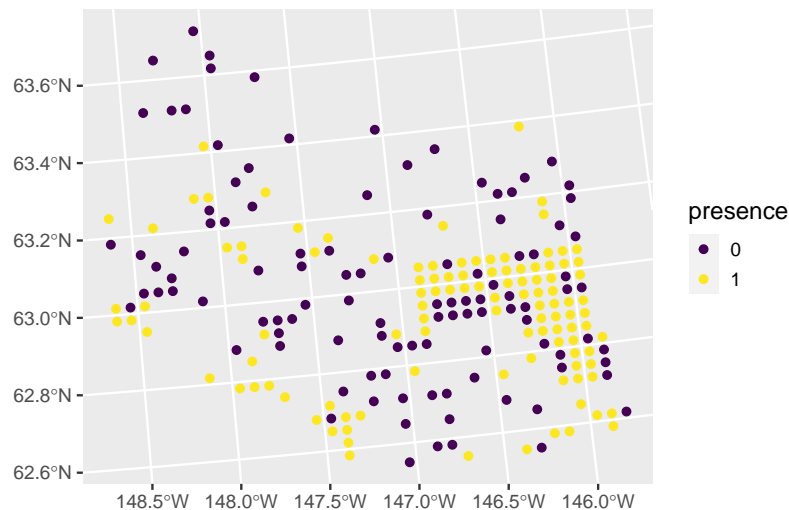


Figure 8: Distribution of moose presence in Alaska. presence equals one if at least one moose was observed at the site and zero otherwise.

One example of a generalized linear model is a binomial (e.g., logistic) regression model. Binomial regression models are often used to model presence data such as these. To quantify the relationship between moose presence and elevation, we fit a spatial binomial regression model (a specific spatial generalized linear model) by running

```
binmod <- spglm(presence ~ elev, family = "binomial",
  data = moose, spcov_type = "exponential")
```

The estimation method is specified via the `estmethod` argument, which has a default value of `"reml"` for restricted maximum likelihood. The other estimation method is `"ml"` for maximum likelihood.

We summarize the fitted model by running

```
summary(binmod)
```

```
#>
#> Call:
#> spglm(formula = presence ~ elev, family = "binomial", data = moose,
#>       spcov_type = "exponential")
#>
#> Deviance Residuals:
#>      Min       1Q   Median       3Q      Max
#> -1.5249 -0.8114  0.5600  0.8306  1.5757
#>
#> Coefficients (fixed):
#>              Estimate Std. Error z value Pr(>|z|)
#> (Intercept) -0.874038   1.140953  -0.766   0.444
#> elev         0.002365   0.003184   0.743   0.458
#>
#> Pseudo R-squared: 0.00311
#>
```

```
#> Coefficients (exponential spatial covariance):
#>      de      ie      range
#> 3.746e+00 4.392e-03 3.203e+04
#>
#> Coefficients (Dispersion for binomial family):
#> dispersion
#>      1
```

Similar to summaries of `glm()` objects, summaries of `spglm()` objects include the original function call, summary statistics of the deviance residuals, and a coefficients table of fixed effects. The logit of moose presence probability does not appear to be related to elevation, as evidenced by the large p-value associated with the asymptotic z-test. A pseudo r-squared is also returned, which quantifies the proportion of variability explained by the fixed effects. The spatial covariance parameters and dispersion parameter are also returned. The dispersion parameter is estimated in some spatial generalized linear models and changes the mean-variance relationship of \mathbf{y} . For binomial regression models, the dispersion parameter is not estimated and is always fixed at one.

We tidy, glance, and augment the fitted model by running

```
tidy(binmod)
```

```
#> # A tibble: 2 x 5
#>   term      estimate std.error statistic p.value
#>   <chr>      <dbl>    <dbl>    <dbl>    <dbl>
#> 1 (Intercept) -0.874      1.14     -0.766    0.444
#> 2 elev         0.00237   0.00318     0.743    0.458
```

```
glance(binmod)
```

```
#> # A tibble: 1 x 9
#>       n      p npar value   AIC  AICc logLik deviance pseudo.r.squared
#>   <int> <dbl> <int> <dbl> <dbl> <dbl> <dbl>    <dbl>         <dbl>
#> 1   218     2     3  692.  698.  698.  -346.    190.         0.00311
```

```
augment(binmod)
```

```
#> Simple feature collection with 218 features and 7 fields
#> Geometry type: POINT
#> Dimension: XY
#> Bounding box: xmin: 269085 ymin: 1416151 xmax: 419057.4 ymax: 1541016
#> Projected CRS: NAD83 / Alaska Albers
#> # A tibble: 218 x 8
#>   presence elev .fitted .resid .hat .cooksd .std.resid
#>   * <fct>   <dbl>   <dbl> <dbl> <dbl>   <dbl>    <dbl>
#> 1 0         469.   0.150 -0.571 0.0500 0.00904   -0.586
#> 2 0         362.   0.107 -0.477 0.0168 0.00198   -0.481
#> 3 0         173.   0.104 -0.468 0.00213 0.000235  -0.469
#> 4 0         280.   0.0939 -0.444 0.00616 0.000615  -0.445
#> 5 0         620.   0.198 -0.664 0.136 0.0402   -0.714
#> 6 0         164.   0.130 -0.528 0.00260 0.000364  -0.528
#> 7 0         164.   0.135 -0.538 0.00269 0.000392  -0.539
#> 8 0         186.   0.166 -0.603 0.00332 0.000607  -0.604
#> 9 0         362.   0.168 -0.606 0.0245 0.00474   -0.614
#> 10 0        430.   0.225 -0.714 0.0528 0.0150   -0.734
#> # ... with 208 more rows, and 1 more variable: geometry <POINT [m]>
```

5.9.2 Prediction

For spatial generalized linear models, we are predicting the mean of the process generating the observation (which includes the spatial effects) rather than the observation itself. We make predictions of moose presence probability at the locations in `moose_preds` by running

```
moose_preds$preds <- predict(binmod, newdata = moose_preds, type = "response")
```

The `type` argument specifies whether predictions are returned on the link or response (inverse link) scale.

We visualize these predictions by running

```
ggplot(moose_preds, aes(color = preds)) +  
  geom_sf(size = 2) +  
  scale_color_viridis_c(limits = c(0, 1)) +  
  theme_gray(base_size = 14)
```

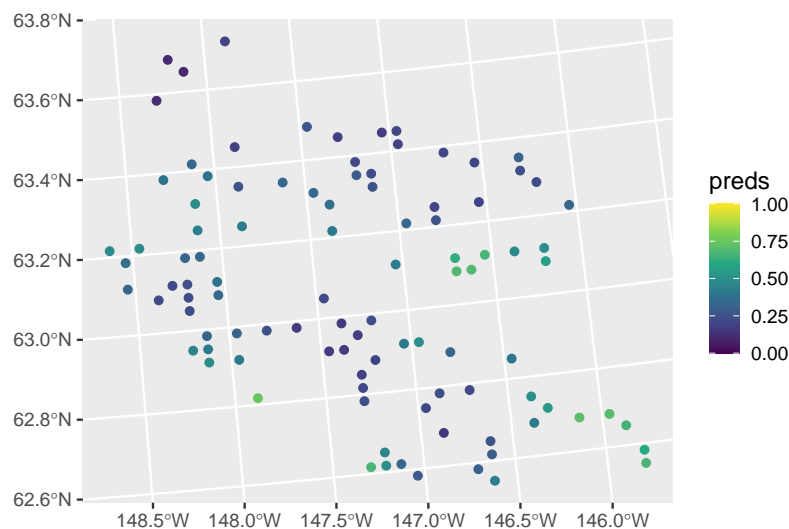


Figure 9: Distribution of moose presence probability predictions in Alaska.

These predictions have similar spatial patterns as moose presence the observed data. Next we remove the model predictions from `moose_preds` and show how `augment()` can be used to obtain the same predictions alongside prediction intervals (on the response scale):

```
moose_preds$preds <- NULL  
augment(binmod, newdata = moose_preds, type = "response", interval = "prediction")
```

```
#> Simple feature collection with 100 features and 5 fields  
#> Geometry type: POINT  
#> Dimension: XY  
#> Bounding box: xmin: 269386.2 ymin: 1418453 xmax: 419976.2 ymax: 1541763  
#> Projected CRS: NAD83 / Alaska Albers  
#> # A tibble: 100 x 6  
#>   elev strat .fitted .lower .upper geometry  
#>   * <dbl> <chr>   <dbl> <dbl> <dbl> <POINT [m]>  
#> 1  143. L      0.705 0.248  0.946 (401239.6 1436192)  
#> 2  324. L      0.336 0.0373 0.868 (352640.6 1490695)  
#> 3  158. L      0.263 0.0321 0.792 (360954.9 1491590)  
#> 4  221. M      0.243 0.0360 0.734 (291839.8 1466091)
```

```
#> 5 209. M      0.742 0.270  0.957 (310991.9 1441630)
#> 6 218. L      0.191 0.0196 0.736 (304473.8 1512103)
#> 7 127. L      0.179 0.0226 0.673 (339011.1 1459318)
#> 8 122. L      0.241 0.0344 0.738 (342827.3 1463452)
#> 9 191. L      0.386 0.0414 0.902 (284453.8 1502837)
#> 10 105. L     0.494 0.114  0.882 (391343.9 1483791)
#> # ... with 90 more rows
```

5.9.3 Simulating Spatial Generalized Data

Several functions exist to simulate spatial generalized data: `sprbinom()` for binomial random variables; `sprbeta()` for beta random variables; `sprpois()` for Poisson random variables; `sprnbinom()` for negative binomial random variables; `sprgamma()` for gamma random variables; and `spinvgauss()` for inverse Gaussian random variables. All of these functions share similar syntax with `sprnorm()` for simulating spatial Gaussian data and require a `spcov_params()` object. The generalized data simulation functions work by first simulating spatial Gaussian data on the link scale. Then this realization is used as the mean by which to simulate the spatial generalized linear model data.

We recreate `sim_params` and `sim_data` by running

```
sim_params <- spcov_params("exponential", de = 5, ie = 1, range = 0.5)
set.seed(0)
n <- 3000
x <- runif(n)
y <- runif(n)
sim_coords <- tibble::tibble(x, y)
```

We simulate a Bernoulli (binomial with size one) random variable by running

```
sim_response <- sprbinom(sim_params, data = sim_coords, xcoord = x, ycoord = y)
sim_data <- tibble::tibble(sim_coords, sim_response = factor(sim_response))
```

and visualize it by running

```
ggplot(sim_data, aes(x = x, y = y, color = sim_response)) +
  geom_point(size = 1.5) +
  scale_color_viridis_d() +
  theme_gray(base_size = 14)
```

There is noticeable patterning in the response variable (`sim_response`) in the same places where there is noticeable patterning for the spatial Gaussian data. This is expected, as the spatial Gaussian data are used to inform the mean (proportion) parameter of the binomial data. Thus where the mean (proportion) parameter is higher, the more likely the binomial observation takes on the value one (successes are usually coded as a one).

5.9.4 Additional Examples

We previously showed how to use `spmodel` to model binary data via spatial binomial regression. Recall that `spmodel` can also be used to model count data via spatial Poisson regression or spatial negative binomial regression, proportion data via spatial beta regression, and skewed, positive data via spatial gamma regression or spatial inverse Gaussian regression. Next we provide examples of fitting a few of these models.

Poisson regression is used to model count data. To quantify the relationship between moose counts (`count`) and elevation, we fit a spatial Poisson regression model and make predictions by running

```
poismod <- spglm(count ~ elev, family = "poisson",
  data = moose, spcov_type = "exponential")
predict(poismod, newdata = moose_preds)
```

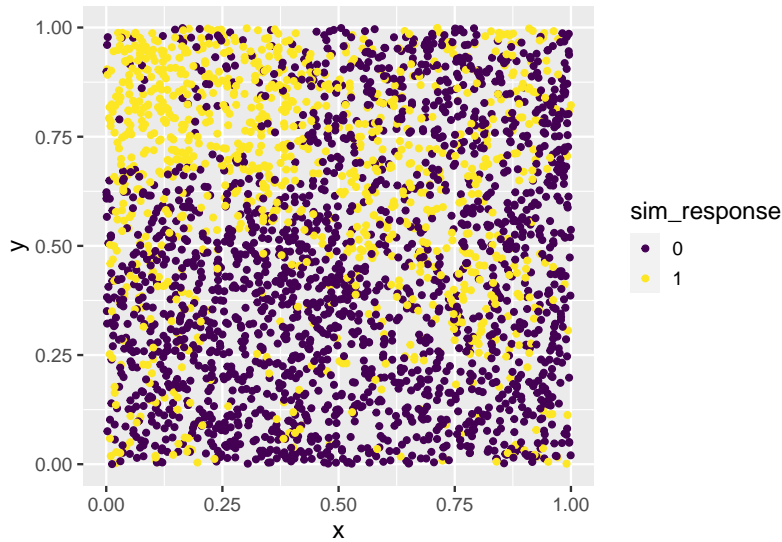


Figure 10: Spatial binomial data simulated in the unit square.

Poisson regression assumes the mean and variance are equal. Often in practice, the variance is larger than the mean. When the variance is larger than the mean, there is said to be overdispersion in the data. Negative binomial regression accounts for overdispersion via an extra dispersion parameter that allows the variance to change separately from the mean (recall the full negative binomial regression parameterization is available in the technical details vignette). We fit a spatial negative binomial regression model to the moose count data and make predictions by running

```
nbmod <- spglm(count ~ elev, family = "nbinomial",
               data = moose, spcov_type = "exponential")
predict(nbmod, newdata = moose_preds)
```

Gamma regression is used to model skewed, positive data. Suppose instead of modeling the `sulfate` data using a spatial linear model, we modeled sulfate using spatial gamma regression. We fit a spatial gamma regression model to the sulfate data and make predictions by running

```
gammamod <- spglm(sulfate ~ 1, family = "Gamma",
                  data = sulfate, spcov_type = "exponential")
predict(gammamod, newdata = sulfate_preds)
```

6 Discussion

Throughout this vignette, we have shown how to use `spmodel` to fit, summarize, and predict for a variety of spatial statistical models. Spatial linear models for point-referenced data (i.e., geostatistical models) are fit using the `splm()` function while spatial linear models for areal data (i.e., spatial autoregressive models) are fit using the `spautor()` function. Spatial generalized linear models for point-referenced data (i.e., generalized geostatistical models) are fit using the `spglm()` function while spatial generalized linear models for areal data (i.e., spatial generalized autoregressive models) are fit using the `spgautor()` function. Several model-fit statistics and diagnostics are available. The broom functions `tidy()` and `glance()` are used to tidy and glance at a fitted model. The broom function `augment()` is used to augment `data` with model diagnostics and augment `newdata` with predictions. Several advanced features are available to accommodate fixed covariance parameter values, random effects, partition factors, anisotropy, simulated data, big data approximations, and random forests for model fitting and prediction.

We appreciate feedback from users regarding `spmodel`. To learn more about how to provide feedback or

contribute to `spmodel`, please visit our GitHub repository at <https://github.com/USEPA/spmodel>.

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Appendices

A An Additional Example Using `caribou`

The purpose of this example is to show more applications of the `splm()` and `spautorm()` functions when the data are not an `sf` object, as well as to show a few other functions in `spmodel`. The `caribou` data are designed experiment with two treatments observed on an equally spaced grid and can be analyzed as point-referenced or areal data. We view the first few rows of `caribou` by running

```
caribou
```

```
#> # A tibble: 30 x 5
#>   water tarp      z      x      y
#>   <fct> <fct> <dbl> <dbl> <dbl>
#> 1 Y     clear  2.42     1     6
#> 2 Y     shade  2.44     2     6
#> 3 Y     none   1.81     3     6
#> 4 N     clear  1.97     4     6
#> 5 N     shade  2.38     5     6
#> 6 Y     none   2.22     1     5
#> 7 N     clear  2.10     2     5
#> 8 Y     clear  1.80     3     5
#> 9 Y     shade  1.96     4     5
#> 10 Y    none   2.10     5     5
#> # ... with 20 more rows
```

First we analyze `caribou` as point-referenced data. Because `caribou` is not an `sf` object, we must provide the columns in `caribou` that represent the x-coordinates and y-coordinates. We fit a spatial linear model regressing nitrogen percentage (`z`) on water presence (`water`) and tarp cover (`tarp`) by running

```
cariboumod <- splm(z ~ water + tarp, data = caribou,
                  spcov_type = "exponential", xcoord = x, ycoord = y)
```

An analysis of variance can be conducted to assess the overall impact of the `tarp` variable, which has three levels (clear, shade, and none), and the `water` variable, which has two levels (water and no water). We perform an analysis of variance and tidy the results by running

```
tidy(anova(cariboumod))
```

```
#> # A tibble: 3 x 4
#>   effects      df statistic p.value
#>   <chr>    <int>    <dbl>   <dbl>
#> 1 (Intercept)     1    43.5 4.33e-11
#> 2 water           1     1.66 1.98e- 1
#> 3 tarp           2    15.4 4.51e- 4
```

There is significant evidence that at least one tarp cover impacts nitrogen. Note that, like in `summary()`, these p-values are associated with an asymptotic hypothesis test (here, an asymptotic Chi-squared test).

Next we analyze `caribou` as areal data. Because `caribou` is not an `sf` object, we must create a weights matrix. We define two observations as neighbors if they are adjacent (directly east, west, north, or south) to one another. Two observations in `caribou` are adjacent if the distance between them equals one (recall that observations are not neighbors with themselves):

```
coords <- cbind(caribou$x, caribou$y)
dists <- as.matrix(dist(coords))
W <- dists == 1
```

Currently, `W` is a logical matrix with `TRUE`s and `FALSE`s. We coerce it to a numeric matrix by running

```
W <- W * 1
```

The ij th value in W is 1 if the observation in the i th row is neighbors with the observation in the j th row and 0 otherwise. We fit a spatial autoregressive model regressing the nitrogen percentage (z) on water presence ($water$) and tarp cover ($tarp$) by running

```
cariboumod <- spautorm(z ~ water + tarp, data = caribou,  
                      spcov_type = "car", W = W)
```

We perform an analysis of variance and tidy the results by running

```
tidy(anova(cariboumod))
```

```
#> # A tibble: 3 x 4  
#>   effects      df statistic    p.value  
#>   <chr>      <int>      <dbl>    <dbl>  
#> 1 (Intercept)      1      714.  2.36e-157  
#> 2 water            1       1.82  1.77e- 1  
#> 3 tarp            2       15.1  5.17e- 4
```

There is significant evidence that at least one tarp cover impacts nitrogen. Note that, like in `summary()`, these p-values are associated with an asymptotic hypothesis test (here, an asymptotic Chi-squared test).

B Random Effect Syntax

A couple of common ways to specify random effects in the `random` argument to `splm()` or `spautorm()` include:

- `~ (1 | group)`: Random intercepts for each level of `group`. `~ group` is shorthand for `~ (1 | group)`.
- `~ (var | group)`: Random intercepts for each level of `group` and random slopes that depend on the variable `var` for each level of `group`.

Some additional syntax for more complicated random effects structures include:

- `~ (var - 1 | group)`: Random slopes (without intercepts) that depend on the variable `var` for each level of `group`.
- `~ (1 | group:subgroup)`: Random intercepts for each combination of levels in `group` and levels in `subgroup`. `~ group:subgroup` is shorthand for `~ (1 | group:subgroup)`.
- `~ (var | group:subgroup)`: Random intercepts for each combination of levels in `group` and levels in `subgroup` and random slopes that depend on the variable `var` for each combination of levels in `group` and levels in `subgroup`.
- `~ (var - 1 | group:subgroup)`: Random slopes (without intercepts) that depend on the variable `var` for each combination of levels in `group` and levels in `subgroup`.
- `~ (1 | group/subgroup)`: Shorthand for `~ (1 | group) + (1 | group:subgroup)`. Commonly, the `group/subgroup` notation implies `subgroup` is nested within `group`.
- `~ (var | group/subgroup)`: Shorthand for `~ (var | group) + (var | group:subgroup)`. Commonly, the `group/subgroup` notation implies `subgroup` is nested within `group`.
- `~ (var - 1 | group/subgroup)`: Shorthand for `~ (var - 1 | group) + (var - 1 | group:subgroup)`. Commonly, the `group/subgroup` notation implies `subgroup` is nested within `group`.

Distinct random effects terms are separated in `random` by `+`. Each term must be wrapped in parentheses. For example, to incorporate random intercepts for `group` and `subgroup`, `random` looks like `~ (1 | group) + (1 | subgroup)`. For random intercepts, recall that `~ group` is shorthand for `~ (1 | group)`. Thus, an equivalent representation of `~ (1 | group) + (1 | subgroup)` is `~ group + subgroup`. Note that for both random intercepts and random slopes, the variable on the right-hand side of `|` (i.e., `group`, `subgroup`, `group:subgroup`) must be a factor (or character) variable.